Constructing Lower-Bounds for CTL Escape Rates in Early SIV Infection

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Abstract
Intrahost human and simian immunodeficiency virus (HIV and SIV) evolution is marked by repeated viral escape from cytotoxic T-lymphocyte (CTL) response. Typically, the first such CTL escape starts around the time of peak viral load and completes within one or two weeks. Many authors have developed methods to quantify CTL escape rates, but existing methods depend on sampling at two or more timepoints. Since many datasets capture the dynamics of the first CTL escape at a single timepoint, we develop inference methods applicable to single timepoint datasets. To account for model uncertainty, we construct estimators which serve as lower bounds for the escape rate. These lower-bound estimators allow for statistically meaningful comparison of escape rates across different times and different compartments. We apply our methods to two SIV datasets, showing that escape rates are relatively high during the initial days of the first CTL escape and drop to lower levels as the escape proceeds.

1 Introduction
During HIV and SIV infections, the viral population repeatedly escapes from selective pressure exerted by cytotoxic T-lymphocytes (CTLs), a type of immune system cell. Each CTL targets a specific peptide, referred to as an epitope, associated with a locus on the viral genome. Mutation at the locus may change the epitope, making it partially or completely unrecognisable by existing CTLs. Viruses possessing such mutations are at a selective advantage, leading to a selective sweep referred to as a CTL escape. See [18] for a review of CTL escape in both HIV and SIV infection.

In this work, we consider the first CTL escape to occur during an infection. In SIV and HIV infection, CTL response initiates roughly at 14 and 21 days after infection, respectively, just prior to peak viral load [8, 10, 18, 30]. In the week or two following the initiation of CTL response, CTL escape often occurs at a single targeted epitope [9, 30, 17, 19, 1]. T-cell tetramer studies suggest that this escape is driven by an especially
focused CTL response in comparison to subsequent responses and escapes [40, 43, 42].

Many authors have attempted to quantify the strength of CTL response by measuring the rate at which CTL escape occurs. A commonly used method (e.g. [17, 27, 26, 4, 15]), introduced in [13, 3], fits escape mutation frequencies at two timepoints to a differential equation model. The model fit is determined by a parameter, known as the escape rate, which is used to quantify the strength of CTL response at a given epitope. Since this approach requires frequency data at two timepoints, we call it the two-point method.

Using the two-point method to analyze the first CTL escape is difficult because rarely do both sampled timepoints capture the escape. For example, the first two timepoints available in HIV studies of acute infection are typically in the range of day 30 and 50, e.g. [14, 17]. Using the two-point method on such data estimates escape rates between day 30 and 50, while CTL response is likely strongest prior to day 30. The situation is different for SIV studies. Since the time of infection can be controlled, sampling timepoints can be chosen that straddle day 14, the approximate time of CTL response; for example sampling can occur at days 7 and 21. But usually the CTL escape has not started at day 7, so the two-point method must be applied using data collected at day 21 and a later timepoint, leading to the same difficulties seen in HIV datasets.

Other authors (e.g. [28, 2, 38, 32]) have developed methods based on the standard model of viral dynamics [37, 34]. These methods depend on models with many parameters, in contrast the two-point method depends only on the escape rate and the mutation frequencies at the two timepoints. Further, fitting the standard model and its variants requires multiple timepoints, so the time period to which such escape rate estimates apply is often unclear. Recently, haplotype data has been used to estimate escape rates, but this method is more applicable to later timepoints in infection, when the viral population possesses significant genetic diversity [31].

The rate of CTL escape can be defined in different ways. For example, some authors measure the timespan from initiation of CTL response to the time when mutant frequencies reach a prescribed level [25, 36]. In the two-point method, using the underlying model, the escape rate is the difference between the average CTL kill rate and the fitness cost of mutation [3, 13]. We take this as our definition of the escape rate.

In this work, we develop inference methods for estimating the rate of the first CTL escape using frequency data from a single timepoint. We apply these methods to SIV datasets, a setting in which inference is slightly easier because infection time is typically known, but our methods extend to HIV escape as well. For SIV infection, we have in mind frequency data collected somewhere between days 14 and 28, times that capture the first CTL escape when the mutation frequency is substantial, but before escape at other epitopes has developed. Single timepoint methods have been used to infer early growth rates for cytomegalovirus, a situation in which immune response and viral mutation are less important [11].

The price we pay for using a single timepoint is the need for an underlying model describing viral dynamics and evolution in the early stages of
infection, prior to peak viral load. Specifying such a model is difficult because the dynamics of early SIV and HIV infection are poorly understood. We solve this difficulty by introducing a model that allows for a range of assumptions on early viral dynamics depending on the parameters chosen. Then, in order to cope with the resulting large parameter space, we derive estimators which serve as lower bounds for the escape rate over a large range of possible models.

We apply our methods to the two SIV datasets presented in Bimber et. al. [7] and Vanderford et. al. [41]. By combining lower-bound estimators and the two points method, we are able to compare escape rates between early and late time periods during the first CTL escape, as well as across different compartments. Our results also clarify the role of different modeling assumptions on escape rate inference.

2 Results

2.1 Model

Our model distinguishes between two types of infected cells: wild type and mutant. Wild types contain the epitope at which the first CTL escape occurs; mutants contain a nucleotide mutation at that epitope. \( w(t) \) and \( m(t) \) represent the number of wild type and mutant type, respectively, at \( t \) days post infection. \( f(t) \) represents the mutant frequency at \( t \), i.e. \( f(t) = m(t)/(w(t) + m(t)) \).

The model depends on the seven parameters listed in Table 2.1. To start, we present the model assuming no mutation-associated fitness costs; \( c = 0 \). The parameter \( t_A \) specifies the time, in units of days post infection, when CTL response initiates. Specification of the model splits according to whether times are before or after \( t_A \).

For times prior to \( t_A \), wild type dynamics are specified through the parameter \( r(t) \) and the equation

\[
\frac{dw}{dt}(t) = r(t)w(t). \tag{1}
\]

\( r(t) \) is the wild type growth rate in units of day\(^{-1}\). By choosing \( r(t) \) appropriately, arbitrary profiles for \( w(t) \) are possible, reflecting the flexibility.
of the model.

Given \( w(t) \), the parameters \( \mu \) and \( X(t_A; s) \) specify the distribution of \( m(t_A) \) through the equation

\[
m(t_A) = \sum_{i=1}^{N} X(t_A; s_i).
\]  

The \( s_i \) for \( i = 1, 2, \ldots, N \) are the times prior to \( t_A \) at which a wild type mutated. The \( s_i \) are stochastic and are generated at a non-constant rate \( \mu w(s) \). \( X(t_A; s) \), termed the offspring distribution, gives the number of mutants at time \( t_A \) that descend from a wild type infected cell which mutated at time \( s \). Importantly, \( X(t_A; s) \) is a random variable. When no fitness costs exist, we assume

\[
E[X(t_A, s)] = \exp\left[\int_{s}^{t_A} r(s')ds'\right],
\]  

so that mutants have the same average growth rate as wild types. In (3), \( \exp[x] \) represents the exponential taken to the power of \( x \), i.e. \( e^x \), and \( E[] \) denotes expected value.

To explain \( X(t_A; s) \) more concretely, we provide three examples:

\[
X_1(t_A; s) = \exp\left[\int_{s}^{t_A} r(s')ds'\right],
\]  

\[
X_2(t_A; s) = 2 \ast \text{Bernoulli}(0.5) \ast \exp\left[\int_{s}^{t_A} r(s)ds\right],
\]  

\[
X_3(t_A; s) = H/2 \ast \exp\left[\int_{s}^{t_A} r(s)ds\right].
\]

Above, Bernoulli(0.5) is a Bernoulli random variable with success probability 0.5 and \( H \) is a continuous distribution on \([1, \infty)\) with density \( \frac{2}{y^3} \), a heavy tailed distribution. All three \( X_i(t_A; s) \) satisfy \( E[X_i(t_A; s)] = \exp[\int_{s}^{t_A} r(s')ds'] \), however the variance increases from zero for \( X_1(t_A; s) \) to infinity for \( X_3(t_A; s) \). Little is known about the form of \( X(t_A; s) \) in SIV and HIV infection, but experimental results suggesting that HIV has an effective population size much smaller than its census size could correspond to offspring distributions such as \( X_2(t_A; s) \) or \( X_3(t_A; s) \) [21, 23].

For times after \( t_A \), we switch to a deterministic model. In the datasets considered below, CTL response arises one or two days prior to or just at peak viral load. As discussed below, \( f(t_A) \approx \mu t_A \), leading to \( m(t) \) in the 100s or greater. As several authors have noted, when mutant population size reaches such values, averaging effects reduce the impact of stochasticity and the dynamics become deterministic, see [39, 20, 24, 12]. The stochastic model could be extended past \( t_A \) in cases for which \( m(t_A) \) is modest, see Methods.

After \( t_A \), we model \( w(t) \) and \( m(t) \) through the equations

\[
\frac{dw}{dt}(t) = (r(t) - k(t))w(t),
\]

\[
\frac{dm}{dt}(t) = r(t)m(t) + \mu w(t),
\]
where $k(t)$ is the CTL-mediated killing rate of wild type infected cells between times $t_A$ and $t_F$ in units of day$^{-1}$, see [16] for a similar model. (7) can be recast in terms of mutant frequency $f(t)$ to give:

$$
\frac{df}{dt}(t) = \mu(1 - f(t)) + (k(t) - \mu)f(t)(1 - f(t)).
$$

(8)

To model a fitness cost $c$, we change (8) to

$$
\frac{df}{dt}(t) = \mu(1 - f(t)) + (k(t) - c - \mu)f(t)(1 - f(t)),
$$

and (3) to

$$
E[X(t_A, s)] = \exp\int_{s}^{t_A} (r(s) - c)ds.
$$

(10)

### 2.2 Inference Methods

Let $\hat{f}_{data}$ be the estimate of mutant frequency obtained by sampling viral sequences at time $t_F$. Using $\hat{f}_{data}$, our goal is infer the escape rate $\bar{k} - c$, where $\bar{k}$ is the average kill rate between $t_A$ and $t_F$,

$$
\bar{k} = \frac{1}{t_F - t_A} \int_{t_A}^{t_F} k(s)ds,
$$

and $c$ is the mutation-associated fitness cost. To start, we assume no fitness costs, i.e. $c = 0$, and present three estimators of $\bar{k}$, $\bar{k}_D$, $\bar{k}_G$ and $\bar{k}_R$, referred to as the deterministic, general, and restricted estimator, respectively. $\bar{k}_G$ and $\bar{k}_R$ serve as lower bounds for $\bar{k}$. Towards the end of the section we consider fitness costs, showing that $\bar{k}_G$ and $\bar{k}_R$ are lower bounds for $\bar{k} - c$.

Regardless of the estimator, our approach involves the same steps. We assume the parameters $\mu, t_A, t_F$ are known and based on these parameters, we select a value for $f(t_A)$, labeled $\hat{f}_{silico}$, and a family of profiles $k(t; \bar{k})$. For every possible value of $\bar{k}$, $k(t; \bar{k})$ is a specific CTL kill rate profile with average $\bar{k}$. Then, starting (8) at time $t_A$ with $f(t_A) = \hat{f}_{silico}$, we fit $\bar{k}$ by integrating (8) to time $t_F$ and selecting the $\bar{k}$ satisfying $f(t_F) = \hat{f}_{data}$. The distinction between the three estimators lies in the choice for $\hat{f}_{silico}$ and the family $k(t; \bar{k})$.

To construct $\bar{k}_D$, we take a deterministic approach, using (8) to compute $f(t_A)$. Setting $f(0) = 0$ and integrating (8) to $t_A$ with $k(t) = 0$ gives $f(t_A) = \mu t_A$ and so we set $\hat{f}_{silico} = \mu t_A$. Equivalently, $\hat{f}_{silico} = E[f(t_A)]$, since (8) gives the mean dynamics of $f(t)$, as can be seen by taking the expected value of (2). To build $k(t; \bar{k})$, we assume CTL kill rates are constant once CTL response begins, making $k(t; \bar{k}) = \bar{k}$ for $t \in [t_A, t_F]$.

Given these choices for $\hat{f}_{silico}$ and $k(t; \bar{k})$, $\bar{k}_D$ satisfies the relation:

$$
\hat{f}_{data} = \frac{1}{1 + \frac{\exp[-\bar{k}(t_F - t_A)]}{\mu t_A + \frac{\exp[-\bar{k}(t_F - t_A)]}{1 - \exp[-\bar{k}(t_F - t_A)]}}},
$$

(11)

If we ignore mutations occurring after $t_A$, the two point method with $f(t_A) = \mu t_A$ and $f(t_F) = \hat{f}_{data}$ can be applied, leading to the following...
approximation:

$$\tilde{k}_D \approx \frac{1}{t_F - t_A} \log \left( \frac{\hat{f}_{\text{data}}}{(1 - \hat{f}_{\text{data}})\mu_A} \right).$$ (12)

As we show below through numerical experiments, $\tilde{k}_D$ is a useful estimator. However, $\tilde{k}_D$ often overestimates $\hat{k}$ and we would like estimators which serve as lower bounds for $\hat{k}$ in order to compare escape rates across different times and compartments. To develop an estimator which is less than $\hat{k}$ with confidence $1 - \sigma$, we choose $\hat{f}_{\text{silico}}$ so that $f(t_A) < \hat{f}_{\text{silico}}$ with probability at least $1 - \sigma$ across a range of parametrizations. To choose $k(t; \hat{k})$, we select profiles maximizing the number of mutations occurring after $t_A$ given fixed values of $f(t_A)$ and $\hat{k}$. Overestimating $f(t_A)$ through $\hat{f}_{\text{silico}}$ and maximizing the number of mutations after $t_A$, leads to under-estimates of $\hat{k}$ because less CLT-mediated killing is necessary to achieve $f(t_F) = \hat{f}_{\text{data}}$. See Methods for more details. As a result, under a null model in which $\hat{f}_{\text{data}}$ is generated according to the stochastic model with $\hat{k}$ as the average for the $k(t)$ parameter chosen, estimators constructed in this manner will be less than $\hat{k}$ with probability at least $1 - \sigma$.

To construct $\tilde{k}_G$ we set $\hat{f}_{\text{silico}} = \mu A / \sigma$. For the $k(t; \hat{k})$ profiles see Methods, but roughly we choose profiles which delay most of the killing until time $t_F$. Intuitively, delaying killing allows more mutations to occur after time $t_A$, thereby raising $f(t_F)$. $\tilde{k}_G$ satisfies the relation

$$\hat{f}_{\text{data}} = \frac{1}{1 + \exp\left[\frac{-k_G(t_F - t_A)}{\mu A} + \mu(t_F - t_A)\right]},$$ (13)

which can be solved to find

$$\tilde{k}_G = \frac{1}{t_F - t_A} \log \left( \frac{\hat{f}_{\text{data}}}{\mu A / \sigma + \mu(t_F - t_A)} \right).$$ (14)

$\tilde{k}_G$ is often a poor lower bound; in many cases, it significantly underestimates $\hat{k}$. The poor behaviour derives from the large parameter, namely all choices for $r(t), k(t), X(t_A; s)$. To produce a better lower-bound estimator, we consider smaller parameter spaces by requiring $r(t) \geq r_{\text{min}}$ for $t < t_A$ and $k''(t) < 0$, where $r_{\text{min}} = .8$. $X(t_A; s)$ is allowed to take any value. The restriction $r(t) \geq r_{\text{min}}$ assumes a minimum expansion rate for the number of infected cells prior to CTL response time $t_A$. $k''(t) < 0$ assumes CTL kill rates rise quickest at the beginning of the CTL response. Other restrictions are possible, reflecting different biological assumptions. Assuming these restrictions, $\tilde{k}_R$ is constructed using $\hat{f}_{\text{silico}} = \mu A (1 + 2/(r_{\text{min}} t_A))$ and $k(t; \hat{k}) = k(t - t_A)/(t_F - t_A)$, a linearly increasing profile. $\tilde{k}_R$ satisfies the relation

$$\hat{f}_{\text{data}} = \frac{1}{1 + \exp\left[\frac{-k_R(t_F - t_A)}{\mu A (1 + 2/(r_{\text{min}} t_A)) + \mu(t_F - t_A)}\right]}.$$ (15)
Ignoring mutations after \( t_A \) allows the two-point method to be applied giving the approximation,

\[
\tilde{k}_R \approx \frac{1}{t_F - t_A} \log \left( \frac{\hat{f}_{data}}{1 - \hat{f}_{data} \mu t_A (1 + \frac{2}{\sigma^{t_A}_{min}})} \right),
\]

(16)

Now we consider the presence of a fitness cost \( c \). \( \tilde{k}_G \) and \( \tilde{k}_R \) are constructed assuming no fitness costs, but the two estimators are lower-bounds for the escape rate when fitness costs exist. Between \( t_A \) and \( t_F \), introducing a fitness cost can be seen as a shift of \( k(t) \) to \( k(t) - c \). Correspondingly, \( \tilde{k}_G \) and \( \tilde{k}_R \) shift from lower bounds for \( \tilde{k} \) to lower bounds for \( \tilde{k} - c \). \( \hat{f}_{silico} \) is still an upper bound for \( f(t_A) \) because fitness costs reduce \( f(t_A) \), meaning the probability \( \hat{f}_{silico} \) is greater than \( f(t_A) \) will increase. As a result, \( \tilde{k}_G \) and \( \tilde{k}_R \) are lower-bound for the escape rate in the absence or presence of fitness costs.

In practice, \( \mu \) and \( t_A \) are unknown, but are needed for all three estimation methods. Using the approximate formulas for the three estimators and letting \( t_F - t_A = 7 \), we calculate that mistaking \( \mu \) by a factor of 10 shifts all estimators by roughly .3. The estimators are shifted down as \( \mu \) is increased, so to maintain the lower-bounds \( \mu \) should be overestimated.

As discussed in [28], assuming an epitope composed of roughly 30 nucleotides, a mutation rate of \( 3 \times 10^{-5} \) per base pairing [29], and about 2/3 of mutations being non-synonymous leads to an epitope mutation rate of \( \mu = 6 \times 10^{-4} \) which is likely greater than the true rate.

If the parameter \( t_A \) is less than the true \( t_A \) value, then the true \( k(t) \) will be zero for times greater than the parameter \( t_A \) but less than the true \( t_A \). There is nothing in the model and estimators that prohibits this, except that the restriction \( k''(t) > 0 \) for \( \tilde{k}_R \) will not hold. In contrast, using a \( t_A \) value greater than the true \( t_A \) value will bias the estimators up because more mutants will exist at \( t_A \) then predicted under the model. To preserve lower-bounds, tetramer data should be used to estimate \( t_A \), with underestimation preferred to overestimation.

### 2.3 Numerical Experiments

We conducted numerical experiments to assess the effect of different \( r(t) \), \( k(t) \) and \( X(t_A; s) \) on the inference methods. We considered three different choices for each of \( r(t) \), \( X(t_A; s) \) and \( k(t) \). We set \( \mu = 10^{-4} \), \( t_A = 1 \), \( t_F = 21 \) and assumed no fitness costs. The three choices for \( r(t) \): referred to as constant, logistic, and slow; have the log \( w(t) \) profiles shown in Figure 1. All three profiles satisfy \( w(t_A) = 10^5 \). For \( X(t_A; s) \), the three choices are given by the \( X_1(t_A; s) \), \( X_2(t_A; s) \), \( X_3(t_A; s) \) defined above and are correspondingly labeled no-variance, Bernoulli, and heavy-tail. To define \( k(t) \) on the interval \([t_A, t_F]\), we chose \( k = .8 \) and then considered a constant profile, \( k(t) = k \), a linear increasing profile, \( k(t) = 2k(t - t_A)/(t_F - t_A) \), and a linear decreasing profile, \( k(t) = 2k(t_F - t)/(t_F - t_A) \). All the \( k(t) \) profiles have average kill rate \( \bar{k} = .8 \). The actual \( r(t) \) profiles seen in HIV and SIV infection are unknown and current understanding of \( k(t) \) profiles depends on tetramer and ELISPOT data which may not translate simply to kill rates [40]. We chose our \( r(t) \) and \( k(t) \) profiles as special cases through
which the effect of general profiles can be understood. For example, the slow $r(t)$ profile could be biologically explained as an initial focus of approximately 100 infected cells formed in the first two days of infection, followed by a waiting time until infection spreads to the lymph nodes and gut, but here we present the slow $r(t)$ as a simple profile through which to understand the role of early expansion rates in shaping the stochasticity of early escape.

![Figure 1: $w(t)$ profiles for numerical experiments](image)

Tables 2-4 show results for different combinations of $r(t)$, $X(t_A; s)$, $k(t)$. To produce the tables, we ran 1000 simulations of the stochastic model for each $r(t)$, $X(t_A; s)$, $k(t)$ combination. Each simulation returned a value of $f(t_F)$ (mutant frequency at sample time) which was used by the inference methods to estimate $\bar{k}$. Importantly, to implement the inference methods, we assumed $\mu, t_A, t_F$ were known, but no further information other than $f(t_F)$ was used. Since we are interested in lower bounds, the table gives one-sided 95% CIs, i.e. the range of values seen over the 1000 simulations with the top 50 ignored. The tables use the exact formulas for $\bar{k}_D$, $\bar{k}_G$, and $\bar{k}_R$; approximate formulas yielded similar patterns.

Table 2 examines the effect of the three $r(t)$ profiles on $f(t_F)$ and the $\bar{k}$ estimators. $X(t_A; s)$ and $k(t)$ were fixed as noted. Across the three parametrizations, $f(t_F)$ has significant variance, with the endpoints of the 95% CIs varying by roughly 50% from their averaged value. Variance in $f(t_F)$ translates into error in the $\bar{k}$ estimates. $\bar{k}_D$ is slightly biased down from the true $\bar{k} = .8$ value, but also has significant probability of overestimating $\bar{k}$. For example, with constant $r(t)$, the 95% CI reaches
to .9. Overestimation is reduced under the logistic \( r(t) \) and increases, to a right endpoint value of .97, under the slow \( r(t) \). Intuitively, when the population is large, averaging reduces variance and when the population is small, the probability of mutations occurring is small, also leading to reduced variance. As a result, variance is influenced by the time the wild type population spends at levels of order \( 1/\mu \), a population size at which mutations are likely but not numerous. Under the logistic \( r(t) \), this time period is short. On the other hand, we constructed the slow \( r(t) \) to make this time period long. The constant \( r(t) \) represents a middle ground. General profiles can be understood within this context. Notice that across all three \( r(t) \) profiles, the restricted and general CIs are below \( \bar{k} \).

Table 3 examines the effect of \( X(t_A; s) \). The Bernoulli \( X(t_A; s) \) increases the variance of \( f(t_F) \) leading to wider CIs across all three inference methods. Somewhat surprisingly, the heavy distribution leads to slightly less \( f(t_F) \) variance. While the heavy distribution allows for samples resulting in extremely high values of \( f(t_F) \), such samples have small probability and their occurrence falls outside the 95% CI. Notice, under a Bernoulli \( X(t_A; s) \) and slow \( r(t) \), the restricted method’s CI exceeds \( \bar{k} = .8 \), reflecting the erroneous assumption of \( r(t) \geq r_{\text{min}} \). In contrast, the general estimator’s CI stays below \( \bar{k} = .8 \).

To understand the effect of \( k(t) \) on \( f(t_F) \) and the three estimators, consider \( \hat{k}_D \) as defined through (11); the right hand side of (11) is \( f(t_F) \) under the assumptions \( f(t_A) = \int_{\text{null}} = \mu t_A \) and \( k(t; k) = \hat{k}_D \). The expressions \( \mu t_A \) and \( \mu/\hat{k}_D(1 - \exp[-k(t_F - t_A)]) \) represent the contributions of mutations before and after \( t_A \), respectively, to \( f(t_F) \). When \( \hat{k}_D t_A \) is large, the \( \mu t_A \) term is dominant and \( f(t_F) \) is mostly influenced by mutations occurring prior to \( t_A \). Intuitively, a large kill rate pushes the frequency of wild types down, reducing the number of mutations occurring after \( t_A \), and a large \( t_A \) value increases the number of mutations arising prior to \( t_A \).

<table>
<thead>
<tr>
<th>( r(t) )</th>
<th>( X(t_A; s) )</th>
<th>( k(t) )</th>
<th>( f(t_F) )</th>
<th>( k_D )</th>
<th>( k_R )</th>
<th>( k_G )</th>
</tr>
</thead>
<tbody>
<tr>
<td>constant no-variance constant</td>
<td>[.14, .45]</td>
<td>[.67, .9]</td>
<td>[.46, .69]</td>
<td>[.25, .48]</td>
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<td>logistic no-variance constant</td>
<td>[.15, .37]</td>
<td>[.68, .85]</td>
<td>[.47, .64]</td>
<td>[.26, .43]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>slow no-variance constant</td>
<td>[.11, .57]</td>
<td>[.63, .97]</td>
<td>[.42, .76]</td>
<td>[.21, .55]</td>
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Table 2: Simulation Results : Effect of \( r(t) \)

<table>
<thead>
<tr>
<th>( r(t) )</th>
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<th>( k(t) )</th>
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<td>[.21, .55]</td>
<td></td>
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</tr>
<tr>
<td>slow Bernoulli constant</td>
<td>[.10, .69]</td>
<td>[.61, 1.04]</td>
<td>[.40, .83]</td>
<td>[.19, .62]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>slow heavy constant</td>
<td>[.10, .55]</td>
<td>[.61, .96]</td>
<td>[.40, .75]</td>
<td>[.20, .54]</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 3: Simulation Results : Effect of \( X(t_A; s) \)
dependence on the $k(t)$ profile (results not shown). In contrast, Table 4 shows simulation results under $\bar{k} = .2$, $t_A = 9$, $t_F = 35$. The increasing and decreasing $k(t)$ profiles produce more and less mutations after $t_A$, respectively, with the constant $k(t)$ profile occupying a middle ground. As the results show, producing more mutants after $t_A$ shifts all the CIs to the right. In particular, under the increasing profile the $\bar{k}_D$ CI is largely to the right of the true $\bar{k} = .2$ value. Intuitively, the $\bar{k}_D$ estimator underestimates the number of mutations after $t_A$, causing it to overestimate $\bar{k}$. Notice, $\bar{k}_G$ and $\bar{k}_R$ still serve as lower bounds.

<table>
<thead>
<tr>
<th>$r(t)$</th>
<th>$X(t_A)$</th>
<th>$k(t)$</th>
<th>$f(t_F)$</th>
<th>$\bar{k}_D$</th>
<th>$\bar{k}_R$</th>
<th>$\bar{k}_G$</th>
</tr>
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<tbody>
<tr>
<td>constant</td>
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<td>constant</td>
<td>[.09,.29]</td>
<td>[.10,.16]</td>
<td>[.06,.12]</td>
<td></td>
</tr>
<tr>
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<td>constant</td>
<td>decreasing</td>
<td>[.05,.27]</td>
<td>[.08,.15]</td>
<td>[.04,.11]</td>
<td></td>
</tr>
<tr>
<td>constant</td>
<td>constant</td>
<td>increasing</td>
<td>[.16,.34]</td>
<td>[.13,.17]</td>
<td>[.08,.12]</td>
<td></td>
</tr>
</tbody>
</table>

Table 4: Simulation Results : Effect of $k(t)$

2.4 Datasets

Most existing analyses of CTL escape infer a single rate for the entire escape. For the datasets below, we consider three times: $t_A$, $t_F$ and $t_S$. $t_A$ and $t_F$ are as previously defined, the CTL response time and sampling time, but now we add a second sampling time $t_S$ subsequent to $t_F$. To $t_A$ and $t_F$, we apply the discussed methods, estimating the escape rate between $t_A$ and $t_F$. To $t_F$ and $t_S$, we apply the two point method, estimating the escape rate between $t_F$ and $t_S$. Using the lower-bound estimators $\bar{k}_G$ and $\bar{k}_R$, we investigate whether escape rates from $t_A$ to $t_F$ are greater than escape rates from $t_F$ to $t_S$. In the case of the Vanderford et. al. data, we also compare escape rates across compartments.

Given frequency data, our estimators and the two-point method estimator provide point estimates for the escape rate. When sampling variance associated with the data is included, the point estimates generalize to CIs in a standard way. Conservatively, we assume the frequency data is accurate to roughly 10%, corresponding to 100 viral sequences at each timepoint. The CIs shown below are constructed accordingly. In some of the following figures, sampling variance causes the two-point method CIs to include negative escape rates. As an example of how this might occur, suppose the mutation frequencies provided by the data at times $t_F$ and $t_S$ are $.43$ and $.42$, respectively. Sampling variance allows the true mutation frequencies from which the data was sampled to be, say, $42$ and $43$, reflecting a drop in mutation frequency and a negative escape rate.

2.4.1 Bimber et. al. dataset

The data from Bimber et. al. involves four Mauritian cynomolgus macaques (MCMs) and four Rhesus macaques (RMs). (The full dataset included eight RMs, we considered the four unvaccinated RMs.) We refer the reader to the article and references therein for full details [7]. Briefly,
all animals were intrarectally infected with SIVmac239. The first CTL escape in the MCMs was at the epitope NEF-RM9, while CTL escape first occurred at TAT-SL8 in the RMs. Pyrosequencing of the epitopes was performed at various timepoints. At day 14 after infection, for both MCMs and RMs, the sampled sequences were roughly homogeneous; by days 21 and 28, MCMs and RMs had a significant frequency of escape mutants at NEF-RM9 and TAT-SL8, respectively. Tetramer data showed no CTL response at day 10, but a strong CTL response by day 14. We set $t_A = 12$ with the aim of underestimating $t_A$ but still accounting for no response at day 10. The results reported below are essentially unchanged given $t_A = 10$ or $t_A = 11$. We set $t_F = 21$ and $t_S = 28$ since these were the first sampled timepoints after day 14. Finally, we set $\mu = 6 \times 10^{-4}$ with the aim of overestimating $\mu$.

![Figure 2](image.png)

**Figure 2:** Escape Rates CIs for MCMs in Bimber et. al. Each subfigure represents a single animal. Within each subfigure, the tics labeled D,R,G give escape rate CIs for days 12-21 using, respectively, the deterministic, restricted, and general methods. The right tic gives the escape rate CI for days 21-28 according to the two-point method. All CIs are at 95% significant and include sampling variance.

Figure 2 shows results for the four MCMs. In each subfigure, the three tics to the left give CIs for the deterministic, restricted, and general estimate of the escape rate during days 12-21. The rightmost tic gives the CI for the escape rate during days 21-28 according to the two-point method. As the figure shows, in three of the four animals, the escape rate estimates under $\bar{k}_D$, $\bar{k}_R$, $\bar{k}_G$ for days 12-21 are higher than the two-point
method estimate for days 21-28. Interestingly, animal cy0165, which is the only animal with overlapping two-point and lower-bound CIs, had a weak CD8+ response from day 14 to 21 and a response that was increasing shortly after day 21 (see Figure 3 in Bimber et. al.).

Figure 3: Escape Rates CIs for RMs in Bimber et. al. See Figure 2 for details.

Figure 3 shows analogous results for the four RMs. The pattern is similar to the MCMs, but in this case no tetramer data was available.

2.4.2 Vanderford et. al. dataset

The Vanderford et. al. dataset includes fifteen Rhesus macaques (RMs) infected intravenously with SIVmac239. As in Bimber et. al., the RMs experienced initial escape at TAT-SL8 and escape dynamics were sampled using pyrosequencing at different timepoints in four compartments: viral RNA in the plasma (PL) and genomic DNA from peripheral blood mononuclear cells (PBMC), lymph node biopsies (LN), and rectal mucosa biopsies (RB). Using tetramer data, Vanderford et. al. estimate the frequency of CD8+ T-lymphocytes specific for TAT-SL8 in the different compartments at days 7, 14 and 28.

Vanderford et. al. show that lymph nodes and rectal mucosa are the primary source of TAT-SL8 escape mutants, with escape mutants often first arising in the lymph nodes. Given this result, we focused on comparing rates of escape between the LN and RB compartments. In order to consider escapes starting in lymph nodes, we restricted our attention to animals in which PL, PBMC, and RB epitope frequencies were above 90%
at day 14 and for which LN escape data was available at days 14 and 28 (not all animals were sampled at all timepoints). Six RMs fulfilled these requirements.

For the LN, tetramer data showed a very weak CD8+ response at day 7 but a strong response by day 14. Given this data, we set \( t_A = 9 \) as an underestimate of CTL response time, results were similar for \( t_A = 7 \) and \( t_A = 8 \). \( t_F \) and \( t_S \) were set at 14 and 28, respectively, reflecting the first sampled timepoints at which mutant frequency was significant in the LN. We set \( \mu = 6 \times 10^{-4} \).

For RB we set \( t_A = 9 \), reflecting tetramer data showing a response similar to the LN. We set \( t_F = 28 \); this was the first timepoint at which mutant frequency was significant in the RB. Subsequent to day 28, frequency data was available at day 56, by which time the escape at TAT-SL8 had already ended. As a result, for RB we estimate the escape rate during the single time interval of days 9–28 and solely through our methods. We set \( \mu = 6 \times 10^{-4} \).

Figure 4 gives confidence intervals for the escape rates in the six RMs. Each subfigure corresponds to a single animal. The first tic from the left gives the escape rates in the LN during days 9-14 using the deterministic and general estimators. The second tic gives the escape rate in the LN during days 14-28, constructed using the two-point method. The third tic gives the escape rate in RB during days 9-28, constructed using the deterministic and general estimators. We have not included results for the restricted estimator to make the figure more readable; roughly, the restricted estimator CIs fall midway between the deterministic and general estimator CIs.

Across all animals the deterministic estimator CI predicts a significantly higher LN escape rate during days 9-14 than escape rates inferred for days 14-28 using the two-point method. This pattern is supported by the general estimator for the RMs represented in the top row, but not in the bottom row. However, if instead of assuming \( \mu = 6 \times 10^{-4} \) we set \( \mu = 10^{-4} \), all general estimator CIs are raised above the two-point method CIs.

Similarly, across all animals, the deterministic CIs predict higher RB escape rates during days 9-28 than those seen in the LN during days 14-28. In this case, the general CIs for the RB escape rate are either slightly above or below the LN escape rates in four of the six animals. If \( \mu \) is raised to \( 10^{-4} \), the deterministic and general CIs are shifted up by roughly .13, so all general CIs are above or even with the LN escape rates.

3 Methods

3.1 \( \tilde{k}_G \) and \( \tilde{k}_R \) are lower bounds for \( \tilde{k} \)

Suppose that \( f(t_F) \) is generated through a single simulation of our stochastic model with no fitness costs and using parameters \( r(t), k(t), X(t_A; s) \) and \( \mu, t_A, t_F \). As previously defined, let \( \tilde{k} \) be the average of \( k(t) \) from \( t_A \) to \( t_F \) and let \( f(t_A) \) be the mutant frequency seen during the simulation at time \( t_A \). Here, we would like to show that \( k_G < \tilde{k} \) and \( k_R < \tilde{k} \)
Figure 4: Escape Rates CIs for Vanderford et. al. Each subfigure represents a single animal. Tics, from left to right, represent escape rates in the lymph node during days 9-14, lymph nodes during days 14-28, and rectal biopsies during days 9-28. Within each subfigure, the left-most and right-most tics show the deterministic CI (upper box) and the general lower-bound CI (lower box). The center tic shows the two-point method CI. All CIs are at 95% significance.

with probability $1 - \sigma$ when $\bar{k}_G$ and $\bar{k}_R$ are constructed using $f(t_F)$ and knowledge of $\mu, t_A, t_F$. $\bar{k}_R < \bar{k}$ further requires $r(t)$ and $k(t)$ to fulfill the requirements stated in the Results. We’ll show $\bar{k}_R < \bar{k}$, the arguments for $\bar{k}_G$ are similar.

Between $t_A$ and $t_F$, $f(t)$ satisfies (8). Integrating (8) relates the simulation values $f(t_A), f(t_F), k(t), \bar{k}$ as follows:

$$f(t_A) = \frac{1}{1 + \frac{\exp[-k(t_F-t_A)]}{f(t_A)+\mu\bar{k}}}$$

where

$$\Gamma = \int_{t_A}^{t_F} \exp[\int_{t_A}^{s} ds' k(s')] ds$$

$\bar{k}_R$ is chosen as the $k^2$ value which satisfies the following expression,

$$f(t_A) = \frac{1}{1 + \frac{\exp[-k^2(t_F-t_A)]}{\Gamma_{silico}(k^2)+\mu\bar{k}_{silico}(k^2)}}$$

where

$$\Gamma_{silico}(k^2) = \int_{t_A}^{t_F} \exp[\int_{t_A}^{s} ds' k(s'; k^2)] ds$$
In (20), \( k(s; k^2) = 2k^2(s - t_A)/(t_F - t_A) \), which is the family of kill rate profiles used to construct \( \bar{k}_R \). \( \Gamma_{silico}(k^2) \) essentially reduces to \( \sqrt{\pi(t_F - t_A) / 4k_R} \) seen in (15), but the integral form written above makes the connection to \( \Gamma \) clear.

If in (19) we choose \( k^2 = \bar{k} \), then the right side of (19) will be less than the right side of (17) with probability \( 1 - \sigma \) because we construct \( \bar{f}_{silico} \) to be greater than \( f(t_A) \) with probability \( 1 - \sigma \) and we construct \( k(t; k^2) \) so that \( \Gamma_{silico}(\bar{k}) > \Gamma \). Therefore, to make the equality in (19) true, \( k^2 \) needs to be chosen to make the right side greater. The derivative of the right side in \( k^2 \) is always negative, so we must lower \( k^2 \), meaning \( k_R < \bar{k} \).

3.2 Constructing \( \bar{f}_{silico} \)

Define \( f_{max} \) by \( \bar{f}_{silico} = f_{max} \), working with \( f_{max} \) instead of \( \bar{f}_{silico} \) makes for cleaner formulas. For a confidence level \( \sigma \), we need to construct \( f_{max} \) satisfying

\[
P(f(t_A) > f_{max} \mu t_A) \leq \sigma. \tag{21}\]

To simplify the arguments below, let \( Z(t_A; s) \) be a normalization of \( X(t_A; s) \):

\[
Z(t_A; s) = X(t_A; s)/E[X(t_A; s)] = X(t_A; s)/\left(\frac{w(t_A)}{w(s)}\right). \tag{22}\]

The rightmost equality follows from \( E[X(t_A; s)] = w(t_A)/w(s) \). Intuitively, wild types at time \( s \) collectively produce \( w(t_A) \) offspring at time \( t_A \); so on average, each wild type produces \( w(t_A)/w(s) \) offspring. (A rigorous demonstration follows from rewriting \( w(t_A) \) and \( w(s) \) in terms of \( r(t) \).) Assuming no mutation-associated fitness costs, on average a mutant should produce the same number of offspring prior to CTL response as a wild type.

Using \( Z(t; t_0) \), \( f(t_A) \) can be written as

\[
f(t_A) = \int_0^{t_A} P(\mu w(s) ds) \left[ \frac{w(t_A)}{w(t_A) + m(t_A)} \right] Z(t; t_0)/w(s), \tag{23}\]

where \( P(\mu w(s) ds) \) is a Poisson process which jumps one unit during the time interval \([s, s + \Delta s]\) with probability \( \mu w(s) \Delta s \). The integral above always reduces to the sum (2), with \( s_i \) as the jump times, but the integral form is easier to analyze. Specifically, for an arbitrary integral of such form, \( I = \int_0^{t_A} P(\rho(s) ds) h(s) \), where \( \rho(s) \) and \( h(s) \) play the role of \( \mu w(s) \) and \( Z(t; s)/w(s) \), respectively, the mean and variance of \( I \) are given by

\[
E[I] = \int_0^{t_A} ds \frac{\rho(s)}{h(s)}, \tag{24}\]

\[
V[I] = \int_0^{t_A} ds \frac{\rho(s)}{h^2(s)} \tag{25}\]

and the probability of no jump during a time interval \([0, t_1]\) is given by

\[
\exp[- \int_0^{t_1} ds \rho(s)]. \tag{26}\]
See [22] for a nice introduction to such computations.

Returning to (23), the expression in the brackets, $w(t_A)/w(t_A) + m(t_A)$, is of order $1 - O(\mu t_A)$. Ignoring small second order effects, we keep the 1 and drop the $O(\mu t_A)$, leading to the approximation

$$f(t_A) \approx \int_0^{t_A} P(\mu w(s)ds) \frac{Z(t;s)}{w(s)}$$

(27)

The value of $f_{\text{max}}$ for the general estimator arises from applying a Chebyshev inequality to $E[f(t_A)]$. Since $E[Z(t;s)] = 1$, using (24) we have $E[f(t_A)] = \mu t_A$. Applying a Chebyshev bound gives,

$$P(f(t_A) > f_{\text{max}} \mu t_A) \leq \frac{E[f(t_A)]}{f_{\text{max}} \mu t_A} = \frac{1}{f_{\text{max}}},$$

(28)

and we set $f_{\text{max}} = 1/\sigma$.

To construct $f_{\text{max}}$ for the restricted estimator we apply a Chebyshev bound using the variance, i.e. $V[f(t_A)]$. However, directly applying a Chebyshev bound using the variance does not work. To see this, consider the special case of $Z(t;t_0) = 1$, i.e. no offspring stochasticity, and $r(t) = 1$, which leads to $V[f(t_A)] \approx \mu$. A Chebyshev bound using the second moment gives

$$P(|f(t_A) - \mu t_A| > a \mu t_A) \leq \frac{V[f(t_A)]}{a^2 \mu^2 t_A^2} = \frac{1}{f_{\text{max}} \mu t_A^2},$$

(29)

Bounding the probability by $\sigma$ requires $f_{\text{max}} = O(1/\sqrt{\mu})$, a value greater than for the general estimator. The trouble derives from the heavy tails of $f(t_A)$; intuitively, heavy tails arise from the small probability that a mutation will occur soon after infection.

We handle the heavy tails by lopping them off and computing the variance of what remains, an example will demonstrate the approach. Consider again the case $Z(t;t_0) = 1$ and $r(t) = 1$, and split $f(t_A)$ into $f_{\text{tail}}(t_A)$ and $f_{\text{center}}(t_A)$ according to whether a mutation occurs before or after a time $t_1$.

$$f_{\text{tail}}(t_A) = \int_0^{t_1} P(\mu w(s)ds) \frac{1}{w(s)}$$

(30)

$$f_{\text{center}}(t_A) = \int_{t_1}^{t_A} P(\mu w(s)ds) \frac{1}{w(s)}.$$

$f_{\text{tail}}(t_A)$ is the tail; we choose $t_1$ so the probability of a mutation occurring in this tail is $\sigma/2$, from (26):

$$\exp[-\int_0^{t_1} \mu w(s)] = 1 - \frac{\sigma}{2}$$

(31)

Since $r(t) = 1$, we can calculate $t_1 \approx \log(\sigma/2\mu)$. Turning to $f_{\text{center}}(t_A)$, $V[f_{\text{center}}(t_A)] = 2\mu^2/\sigma$, which gives the Chebyshev bound

$$P(|f_{\text{center}}(t_A) - E[f_{\text{center}}(t_A)]| > a \mu t_A) \leq \frac{2\mu^2/\sigma}{a^2 \mu^2 t_A^2}.$$
To bound $P(f_{center}(t_A) > f_{max}\mu t_A)$ by $\sigma/2$ requires $f_{max} = (1 + 2/\sigma t_A)$, which for $t_A = 14$ is about $1/5$th of the $f_{max} = 1/\sigma$ provided by the general bound. Combining the two $\sigma/2$ bounds above shows $f_{center}(t_A) > f_{max}\mu t_A$ with probability less than $\sigma$.

When offspring stochasticity is present, the tail is not identified with early mutation times because $Z(t; s)$ may itself have a heavy tail, allowing late mutations to produce large numbers of offspring. Instead, the tail corresponds to jumps of large size, meaning jumps of the poisson process $P(\mu w(s)ds)$ for which $Z(t; s)/w(s)$ is large. Once the jumps are re-ordered according to size, the same arguments given in the example can be applied. Technical details provided in the appendix demonstrate $P(f(t_A) > f_{max}\mu t_A) \leq \sigma$ when $f_{max} = 1 + 2/\sigma t_A r_{min}$, a result similar to the example except for the appearance of $r_{min}$.

### 3.3 Construction of $k(t; \tilde{k})$

Before constructing $k(t; \tilde{k})$ for the general and restricted estimators, we explain the dependence of $f(t_F)$ on the profile of $k(t)$. Integrating the $w(t)$ equation in (7) from time $t_A$ to $t_F$ makes the dependence of $w(t_F)$ on $k(t)$ explicit:

$$w(t_F) = w(t_A) \exp\left[ \int_{t_A}^{t_F} r(s)ds \right] \exp\left[ - \int_{t_A}^{t_F} k(s)ds \right].$$

(33)

The second exponential, $\exp\left[ - \int_{t_A}^{t_F} k(s)ds \right]$, represents the contribution of $k(t)$ to $w(t_F)$; notice the exponential can be rewritten as $\exp\left[ - \tilde{k}(t_F - t_A) \right]$, showing that $k(t)$ affects $w(t_F)$ only through $\tilde{k}$.

In contrast, $m(t_F)$ depends on $\tilde{k}$ and the profile of $k(t)$. Consider the ratio $m(t_F)/w(t_F)$, its dependence on $m(t_A)/w(t_A)$ and $k(t)$ is given by

$$\frac{m(t_F)}{w(t_F)} = \exp[\tilde{k}(t_F - t_A)] \left[ \frac{m(t_A)}{w(t_A)} + \mu \Gamma \right],$$

(34)

where $\Gamma$ is defined above in (18).

To obtain the general estimator, we replace $\Gamma$ by an upper bound $t_F - t_A$, thereby achieving the maximum possible value of $m(t_F)/w(t_F)$. Intuitively, once $\tilde{k}$ is chosen, the $k(t)$ profile that maximizes the mutant frequency at $t_A$ delays all of the killing until time $t_F$. Since $\tilde{k}$ is fixed, the number of wild types at $t_F$ is fixed but delaying killing until time $t_F$ raises the number of wild types extant during the interval $t_A$ to $t_F$, thereby raising the number of wild type mutations during that interval and, in turn, the mutant frequency at $t_F$. As a specific example, consider the following $k(t; \tilde{k})$ family of profiles:

$$k(t; \tilde{k}) = \begin{cases} 0 & \text{for } t < t_F - \epsilon \\ \frac{2\tilde{k} \epsilon}{t_F - t} & \text{for } t \geq t_F - \epsilon, \end{cases}$$

(35)

where $\epsilon$ is the length of some small time period prior to $t_F$ during which all the killing occurs. The general bound is achieved by taking $\epsilon \to 0$.

Under the restriction $k''(t) > 0$. An upper bound on $\Gamma$ is achieved using the profile family $k(t; \tilde{k}) = 2\tilde{k}(t - t_A)/(t_F - t_A)$. Intuitively, we
again delay killing, but the restriction \( k''(t) > 0 \) prevents the biologically unrealistic case of all killing occurring at \( t_F \). For \( k(t_F - t_A) > 3 \), which is the regime of all our datasets, \( k(t; \tilde{k}) \) is well approximated by \( \sqrt{\frac{\pi(t_F - t_A)}{4\tilde{k}R}} \).

### 3.4 Model Extension

The switch in the model from stochastic to deterministic dynamics need not occur at \( t_A \). In particular, when \( m(t_A) \) is small, perhaps due to an early immune response, the stochastic dynamics can be extended through a parameter \( t_{\text{switch}} \) which specifies the switch time. Wild type dynamics prior to \( t_{\text{switch}} \) become

\[
\frac{dw}{dt}(t) = (r(t) - k(t))w(t), \tag{36}
\]

where \( k(t) = 0 \) prior to \( t_A \). As before, \( r(t) \) and \( k(t) \) can be specified arbitrarily. Evaluation of \( m(t_A) \) through (2) is replaced by evaluation of \( m(t_{\text{switch}}) \) through

\[
m(t_A) = \sum_{i=1}^{N} X(t_{\text{switch}}; s_i) \tag{37}
\]

and

\[
E[X(t_{\text{switch}}, s)] = \exp\left[\int_{s}^{t_{\text{switch}}} r(s')ds'\right], \tag{38}
\]

Importantly, (36) assumes \( w(t) \) dynamics are independent of \( m(t) \) dynamics, a plausible assumption when mutant frequencies are small. \( t_{\text{switch}} \) should be chosen to satisfy \( f(t_{\text{switch}}) \ll 1 \), to ensure small frequencies, but also to satisfy \( m(t_{\text{switch}}) \gg 1 \), to ensure deterministic dynamics after \( t_{\text{switch}} \). For our datasets \( t_{\text{switch}} = t_A \) satisfies this requirement.

### 4 Discussion

Inferring the rate of the first CTL escape involves a trade-off. On one hand, the existing two-point method is largely model independent but can only be applied using two sampled timepoints, meaning that the early part of the escape is often missed and inference implicitly focuses on later parts of the escape. On the other hand, if a more parametrized method is used, the early part of the escape can be considered but inference results depend on model structure and the parameter values chosen.

In this work, we have developed escape rate inference methods applicable to single timepoint datasets with an effort to minimize model dependence. To do this, we developed a general model and constructed lower-bound estimators valid across large portions of the model’s parameter space.

Lower-bound estimators allow us to compare escape rates in a statistically meaningful way which accounts for model and parameter uncertainty. Through the Bimber et. al. dataset, lower-bound estimates combined with the two-point method reveal faster rates for the first CTL escape during days 7-21 than days 21-28. The Vanderford et. al. data
shows roughly the same pattern, with faster rates of escape in the lymph nodes during days 7-14 than during days 14-28.

In this work, we have not distinguished between different types of epitope mutations, although CTL escape typically involves multiple mutation variants [9]. As CTL binding affinity may differ between mutation variants, we are really inferring an average escape rate over all mutations at the epitope. For TAT-SL8, most mutations arising in escape have low binding affinity, so our estimates may apply without much modification [1, 35]. Nevertheless, more work is required to address this limitation.

Besides developing estimators, our model and accompanying analysis provides a basis through which to understand early infection stochasticity and its impact on escape rate inference. Soon after peak viral load, in both HIV and SIV, multiple CTL escapes occur, often overlapping in time [6, 19, 17, 9]. The interaction of viral variants involved in such sweeps, both through inter-variant competition for target cells and possible recombination events, makes modeling and inference complex [24, 33, 20, 5, 15]. The parameter space becomes much larger, multiple escapes and multiple variants within each escape leads to potentially dozens of parameters. Inferring escape rates in such a high dimensional space through deterministic models will likely lead to overfitting. Extending the current work to multiple escape settings may be helpful in avoiding such difficulties.

The lower-bound estimators as currently constructed are overly conservative. Often, as demonstrated by numerical experiments in the Methods section, the lower-bound CIs significantly underestimate the escape rate. Improved lower-bound estimators require better quantitative understanding of acute infection. For example, the number of offspring infected cells descendant from a single HIV or SIV infected cell is not well understood. Future work leading to improved lower-bound estimators would expand our ability to analyze individual escapes as well as compare escapes against each other.

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References


A Appendix

Here we derive the bound $P(f(t_A) > f_{\text{max}} \mu t_A)$ for $f_{\text{max}} = 1 + \left( \frac{2}{\sigma^2 r_{\text{min}}} \right)^{1/2}$ under the restriction $r(t) \geq r_{\text{min}}$. For simplicity we assume $Z(t_A, s)$ has a density, written as $g(z, s)$ to reflect possible dependence on the mutation time $s$, although the arguments below work for discrete distributions as well. The first few computations below use some basic ideas from the theory of Levy processes, see [22] for an introduction.

To start, we order the jump sizes of $f(t_A)$ so the tail can be identified; this corresponds to writing the Laplace exponent of $f(t_A)$ in standard form. Starting with (27), we can compute the Laplace transform of


density, written as $g(z, s)$ to reflect possible dependence on the mutation time $s$, although the arguments below work for discrete distributions as well. The first few computations below use some basic ideas from the theory of Levy processes, see [22] for an introduction.

To start, we order the jump sizes of $f(t_A)$ so the tail can be identified; this corresponds to writing the Laplace exponent of $f(t_A)$ in standard form. Starting with (27), we can compute the Laplace transform of
\[ f(t_A) \text{ and the associated Laplace exponent } \Psi(\lambda) \text{ (i.e. } E[\exp[-\lambda f(t_A)]] = \exp[-\Psi(\lambda)]): \]
\[ \Psi(\lambda) = \int_0^{t_A} ds \mu w(s) \int_0^\infty dz g(z, s) (1 - \exp[-\lambda \frac{z}{w(s)}]) \quad (39) \]
Changing variables through \( v = w(s) \) and flipping the order of integration gives
\[ \Psi(\lambda) = \int_0^\infty dx \rho(x) (1 - \exp[-\lambda x]) \quad (40) \]
with
\[ \rho(x) = \int_1^{w(t_A)} dv \frac{\mu v^2}{w'(s)} f(xv, s). \quad (41) \]
By well known results in the theory of Levy distributions, \( \rho(x) \) is the rate at which jumps of size \( x \) occur, allowing us to re-express \( f(t_A) \) as
\[ f(t_A) = \int_0^\infty P(\rho(x) dx)x. \quad (42) \]
Beyond this point, the computations only depend on calculus and (24)-(26).
Through (42), the tail of \( f(t_A) \) can be identified, and we split \( f(t_A) \) into two pieces according to whether \( x \) is greater or less than a value \( x_0 \).
\[ f_{\text{tail}}(t_A) = \int_{x_0}^\infty P(\rho(x) dx)x, \quad (43) \]
\[ f_{\text{center}}(t_A) = \int_0^{x_0} P(\rho(x) dx)x \]
We choose \( x_0 \) so the probability of no jump in the tail, i.e. \( f_{\text{tail}}(t_A) = 0 \), is \( \sigma/2 \), which requires
\[ \int_{x_0}^\infty dx \rho(x) = \sigma/2. \quad (44) \]
To identify \( x_0 \), we execute the following arguments.
1. Using the inequality \( w'(s) \geq r_{\min} w(s) \), a consequence of the assumption \( r(t) \geq r_{\min} \), gives the bound
\[ \int_{x_0}^\infty dx \rho(x) \leq \frac{\mu}{r_{\min}} \int_{x_0}^\infty dx \int_1^{w(t_A)} dv f(xv, s) \quad (45) \]
2. Apply the transform \( v' = xv \) to the integral on the right in step 1 to find,
\[ \int_{x_0}^\infty dx \rho(x) \leq \frac{\mu}{r_{\min}} \int_{x_0}^\infty dx \frac{1}{x^2} \int_{x_0}^{x_0 w(t_A)} dv f(v, s) \quad (46) \]
3. Since \( E[Z(t_A; s)] = 1 \), the \( dv \) integral on the right of step 2 is less than 1, leading to
\[ \int_{x_0}^\infty dx \rho(x) \leq \frac{\mu}{x_0 r_{\min}} \quad (47) \]
At the end of these steps we conclude

\[ x_0 \leq \frac{2\mu}{\sigma r_{\text{min}}}. \] (48)

Next, as in the example, we bound the variance of \( f_{\text{center}}(t_A) \).

\[ V[f_{\text{center}}(t_A)] = \int_0^{x_0} dx \rho(x)x^2. \] (49)

Using the same transforms as steps 1 and 3 above,

\[ V[f_{\text{center}}(t_A)] \leq \frac{\mu}{r_{\text{min}}} \int_0^{x_0} dx = \frac{\mu x_0}{r_{\text{min}}} \] (50)

The rest is exactly as in the example.